

Logical Foundations of social influence



understand how human agents reason and behave (empirical)

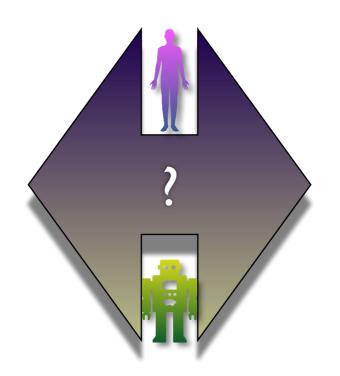
understand how ideally rational agents would behave (theoretical)



Big picture

behavior

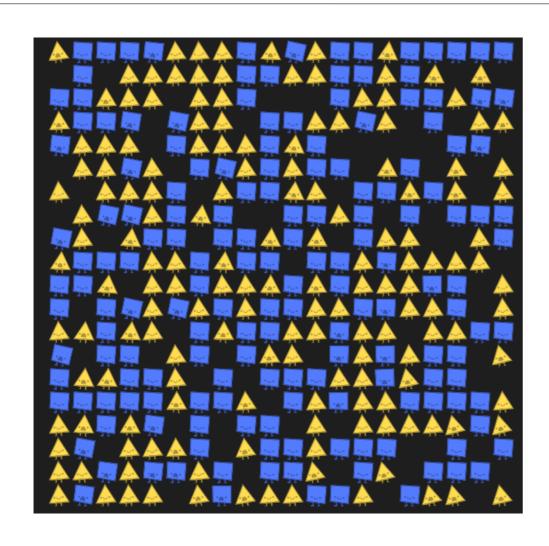






rationality

Example: Schelling's Segregation Model

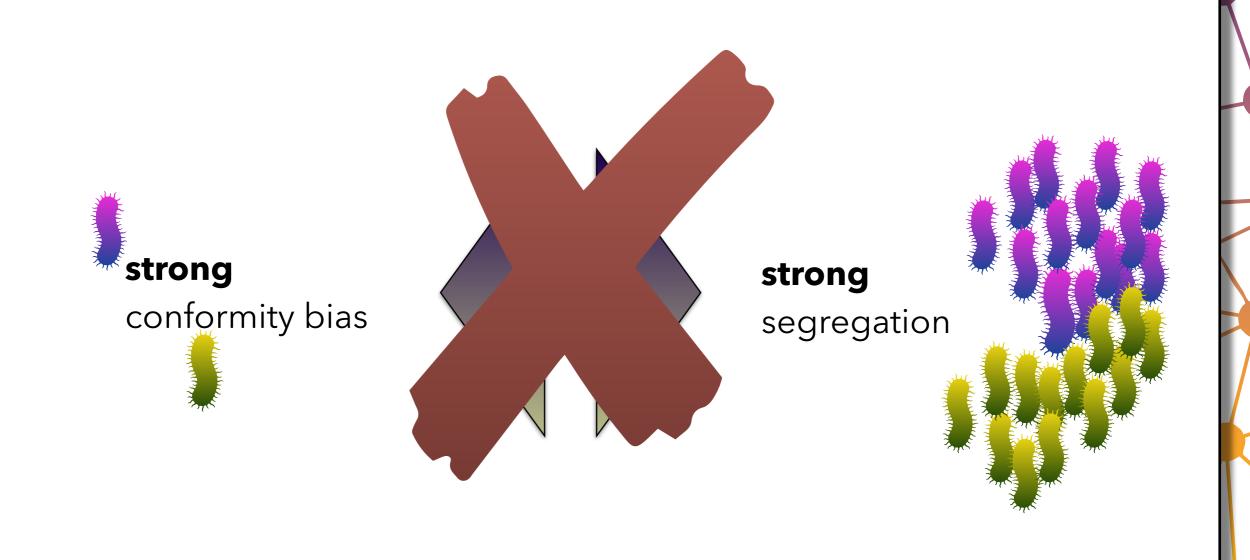


. . . .

 uniform rule: prefer to move if less than 1/3 of your neighbors are of your type

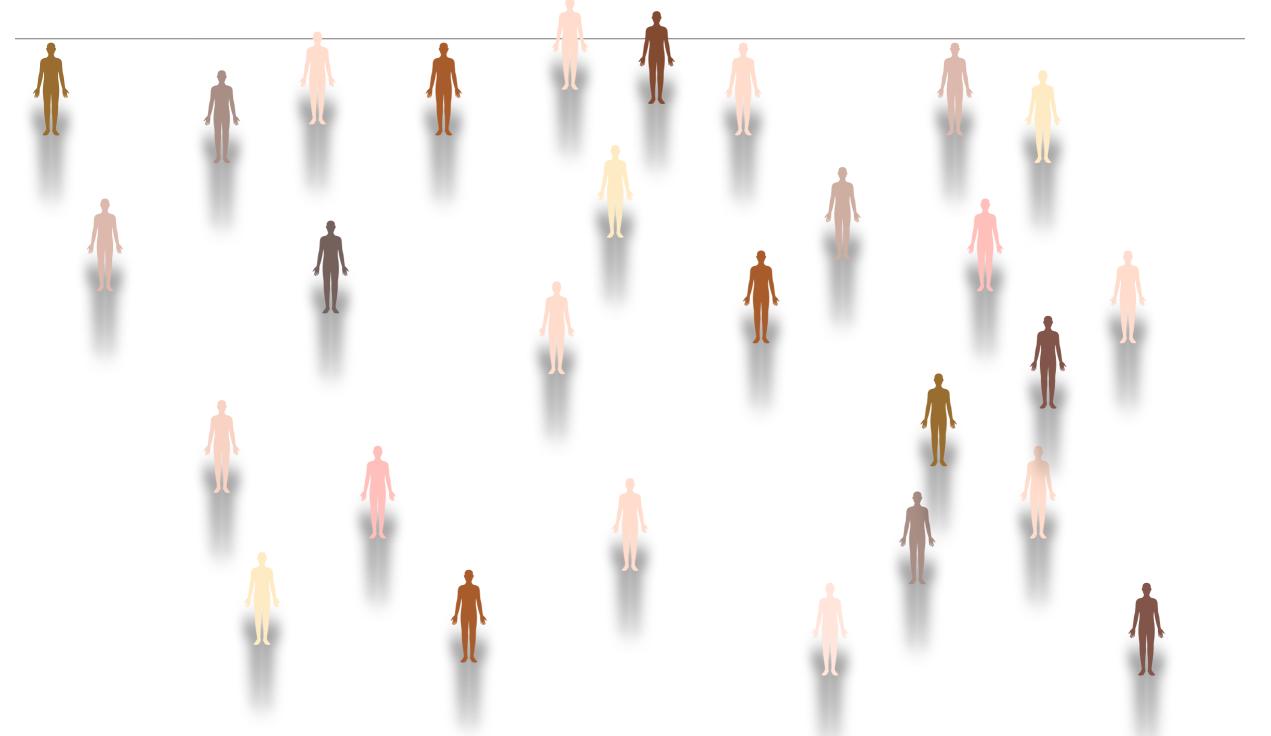
A small individual bias has a huge collective impact.

What does the model show?





Take a bunch of humans



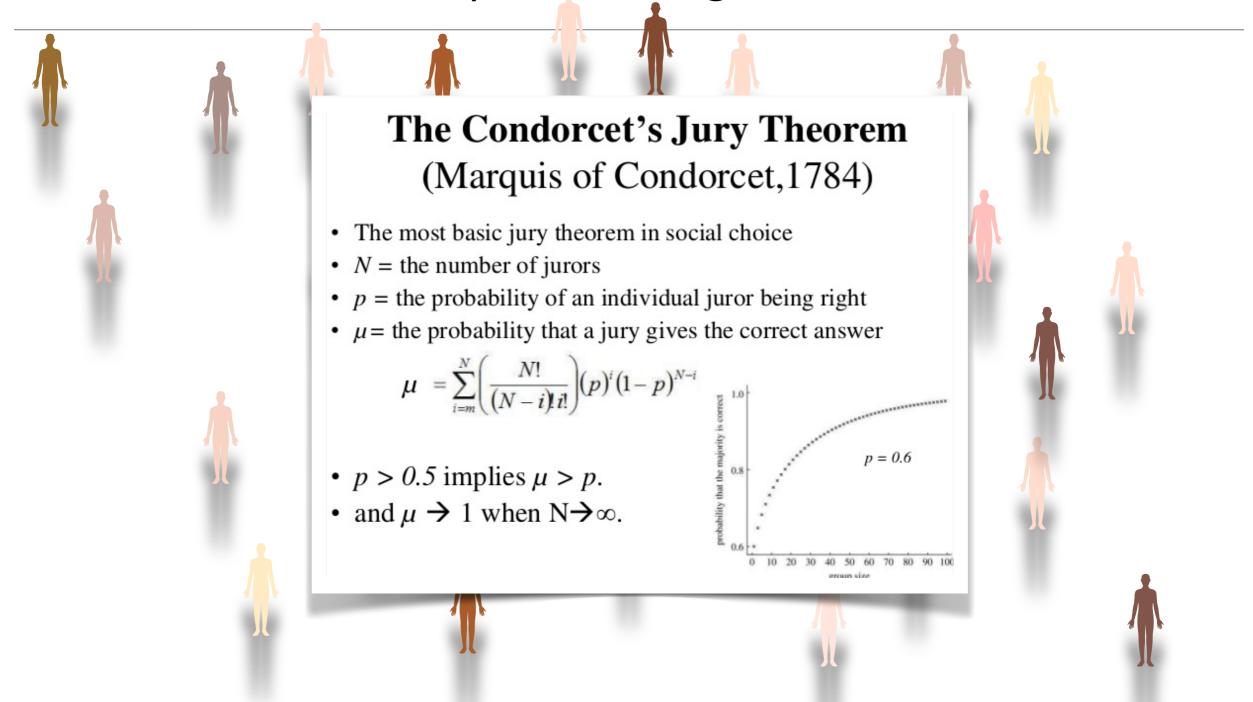
Independent guesses



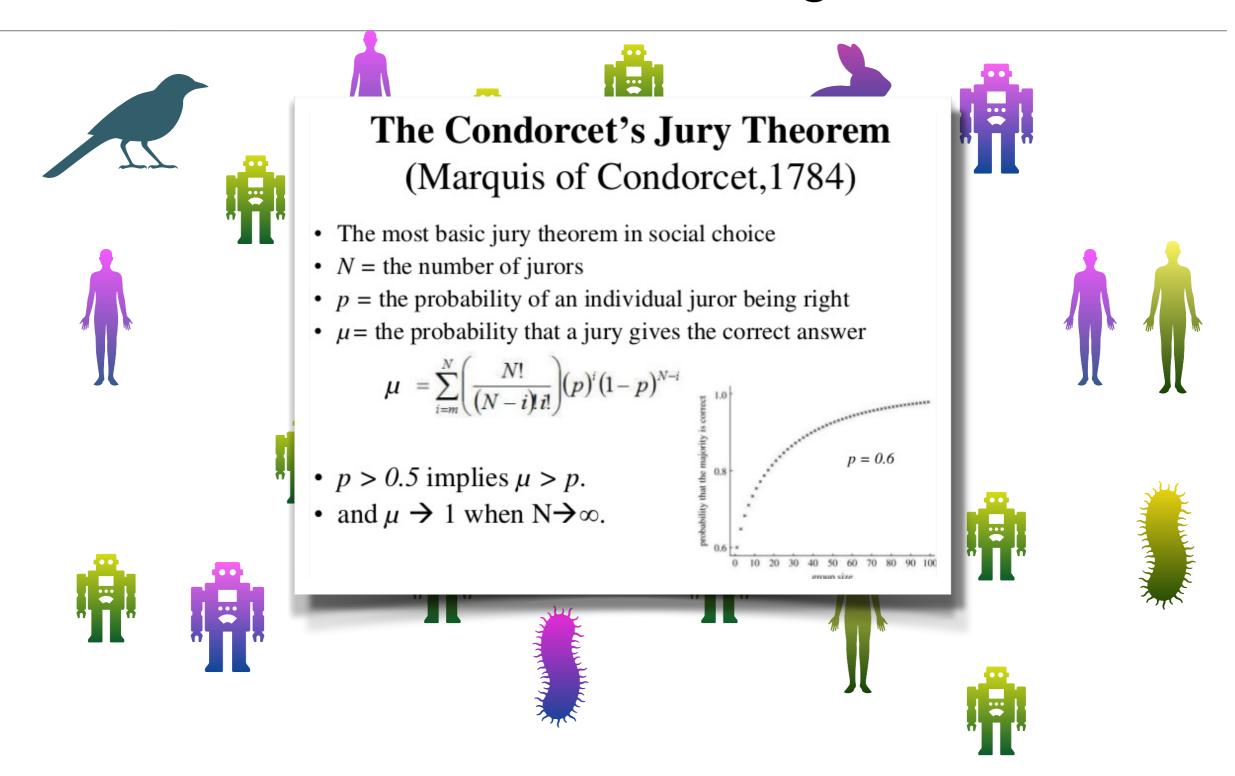
Independent guesses



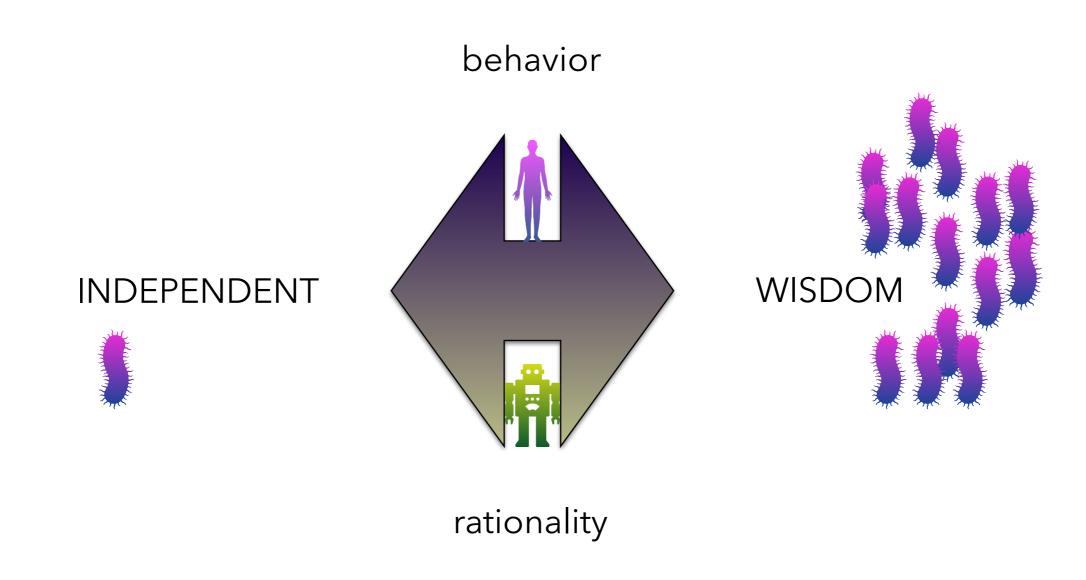
Independent guesses



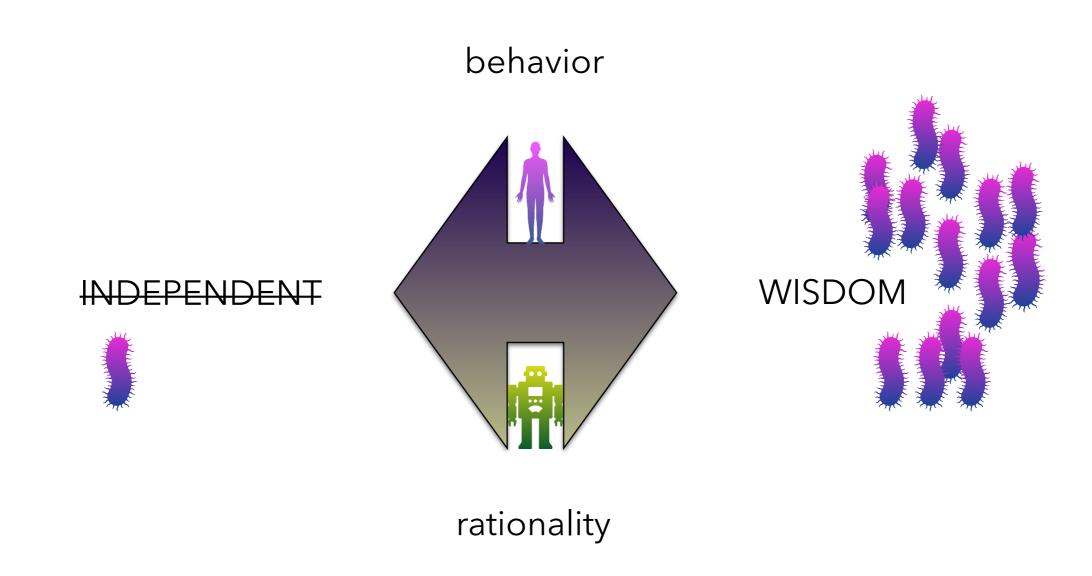
Take a bunch of ... agents



Without social influence



With social influence?

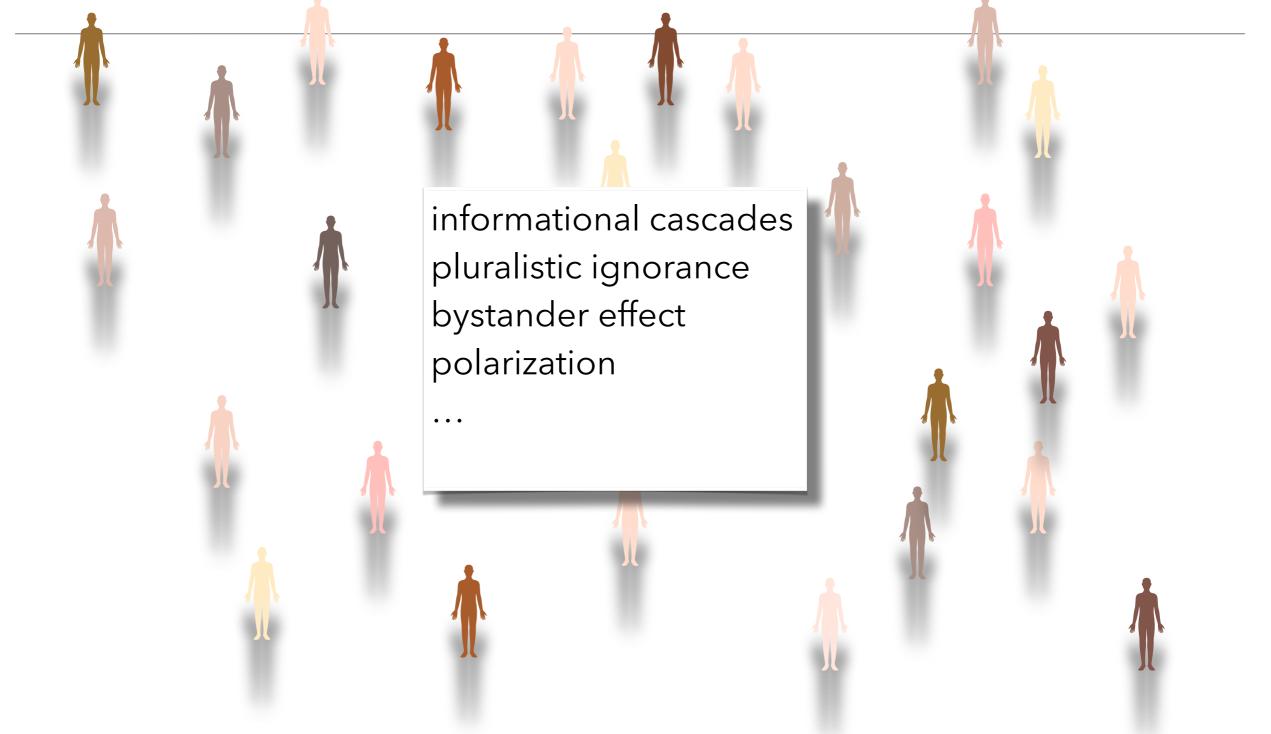


Sometimes...



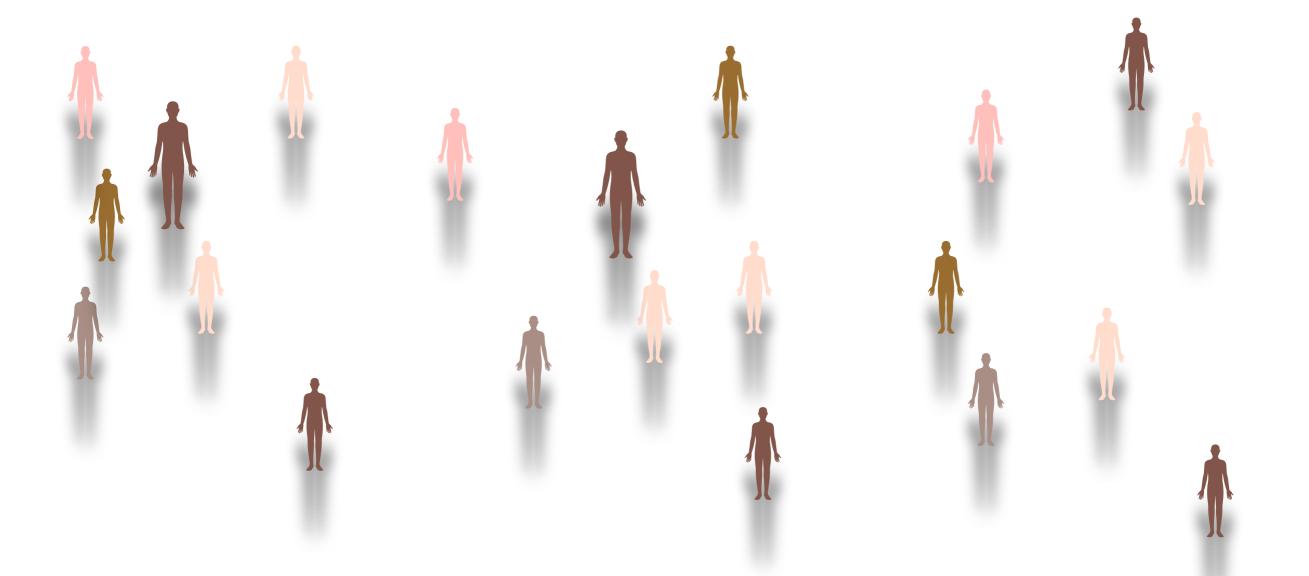
...individuals lead each other in the wrong direction

Correlated behavior and collective failures



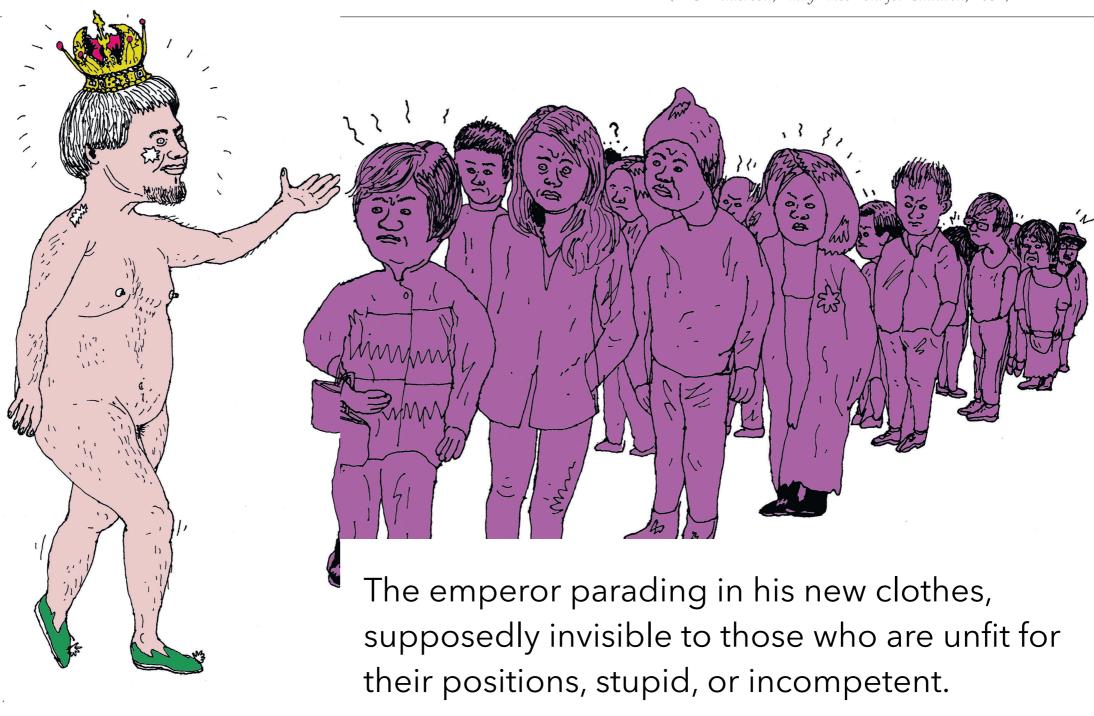
1) Pluralistic ignorance

"a situation where the majority of group members privately rejects the norm, but assumes (incorrectly) that most others accept it" (Katz & Allport 1931:152)



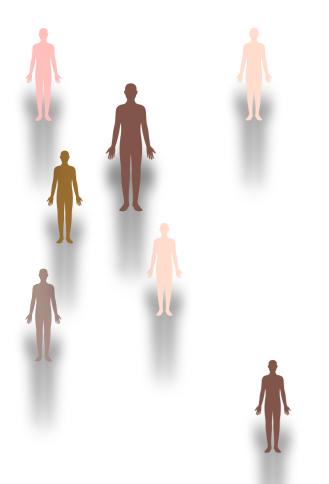
The Emperor's new clothes

(H.C. Anderson, Fairy Tales Told for Children, 1837)



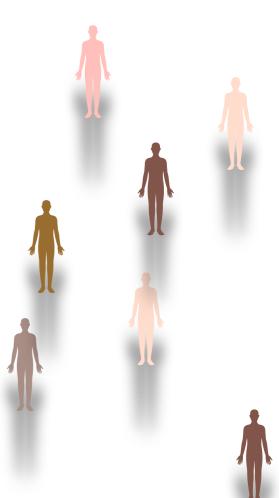
Pluralistic ignorance

"a situation where the majority of group members privately rejects the norm, but assumes (incorrectly) that most others accept it" (Katz & Allport 1931:152)



Documented examples include:

- classroom situations
- college drinking norms
- segregation norms





Private vs Expressed Opinions

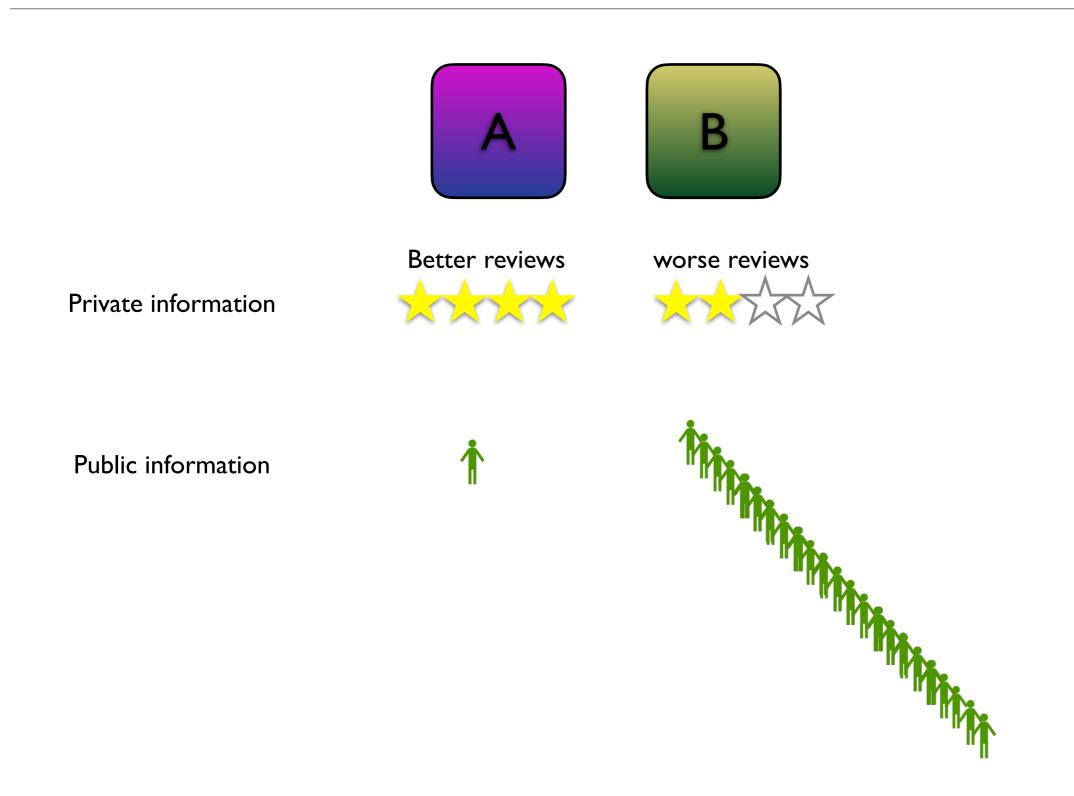


© The New Yorker Collection 1979 Henry Martin from cartoonbank.com. All Rights Reserved.

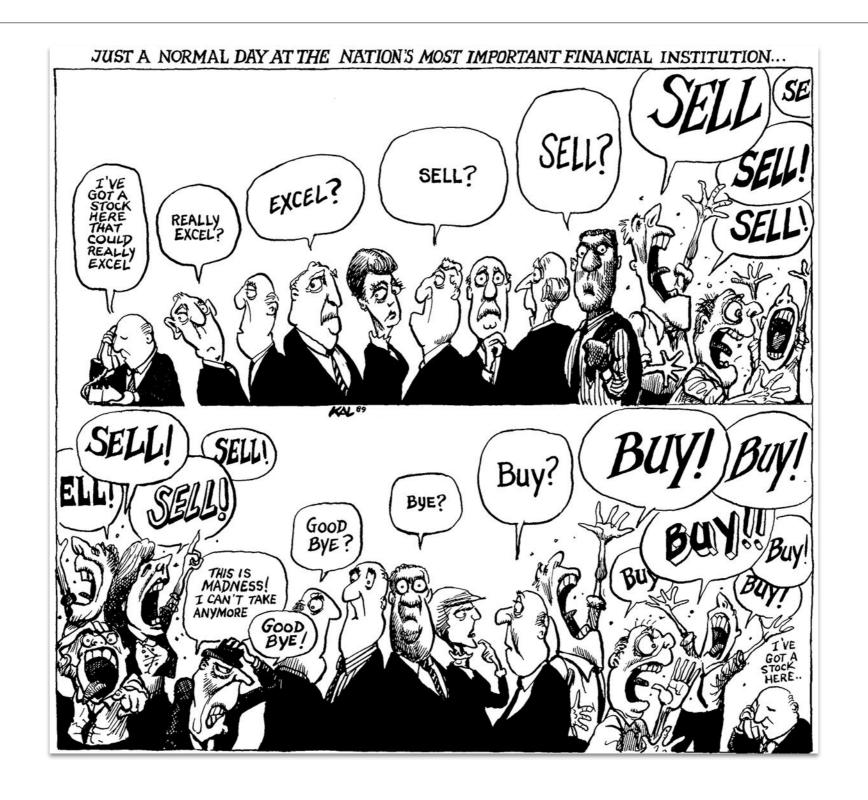
2) Informational Cascades

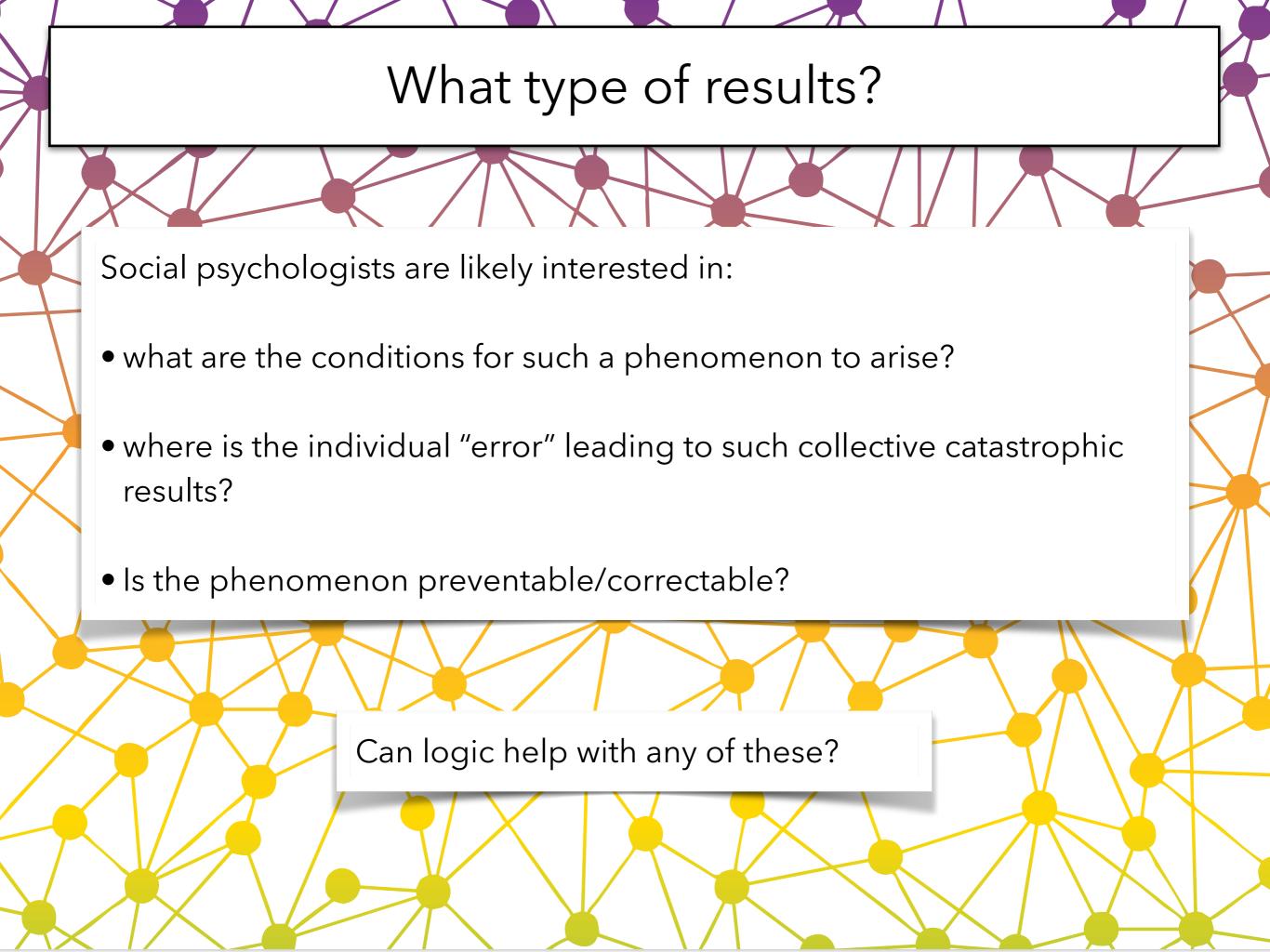
- Agent disregard their own private information to follow the choice of some preceding agents
- All remaining agents pick the same option, even if they have diverging private evidence
- This imitation effect might lead the whole community to make the worst possible choice

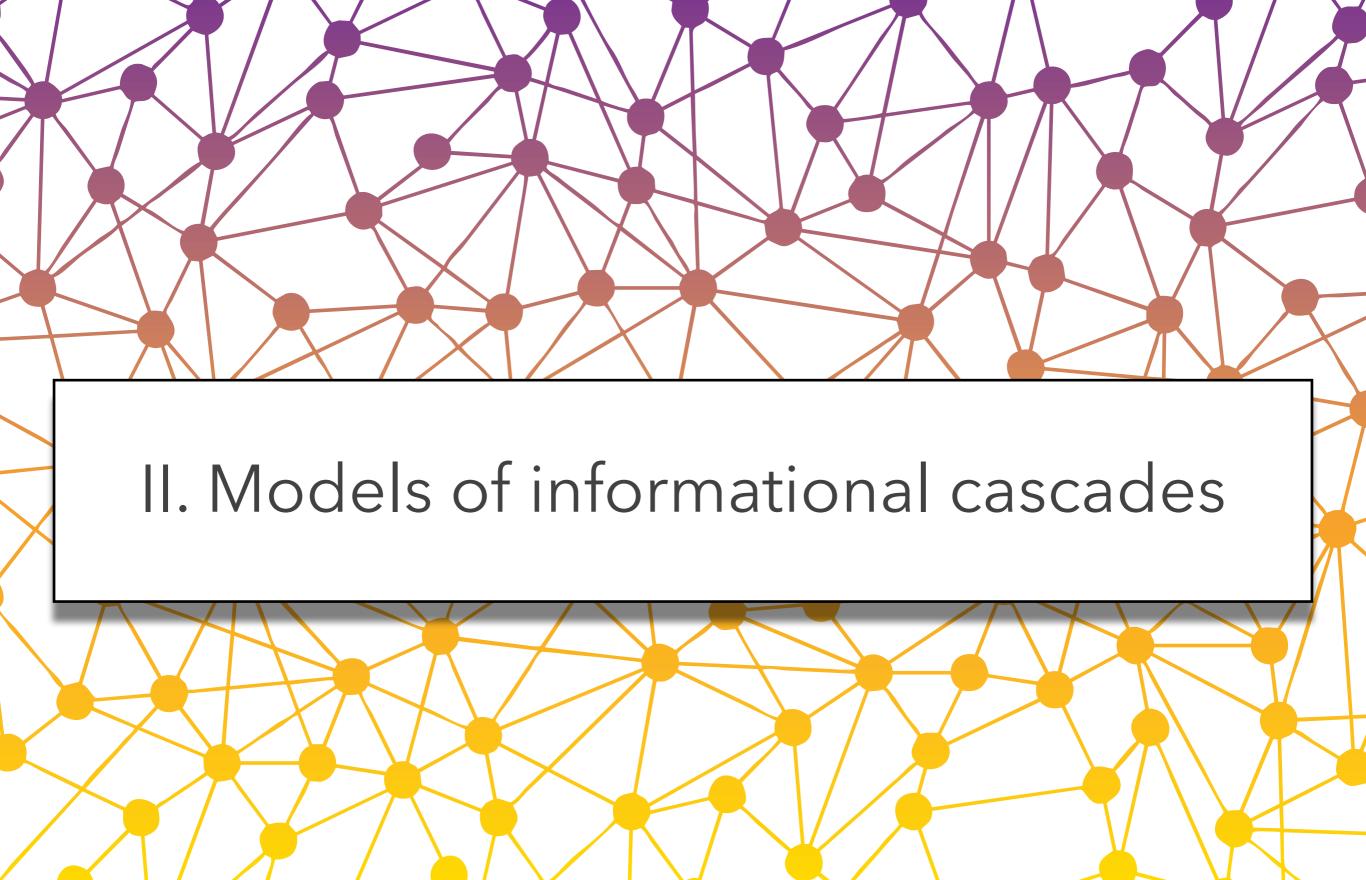
Example: Choose a restaurant



Mindless imitation effects? (again)

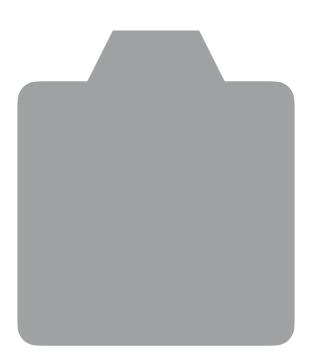






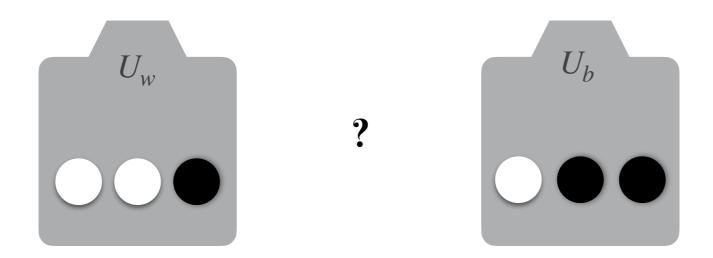
■ Logical Models of Informational Cascades (pdf), Alexandru Baltag, Zoé Christoff, Jens Ulrik Hansen and Sonja Smets, in J. van Benthem and F. Liu (Eds.): Logic across the University: Foundations and Applications, — Proceedings of the Tsinghua Logic Conference, Beijing, 14-16 October 2013, Studies in Logic, Volume 47, pp.405-432, College Publications, London, (2013).

Analysis of a cascade



1 (opaque) urn, containing three marbles

What is the content of the urn?

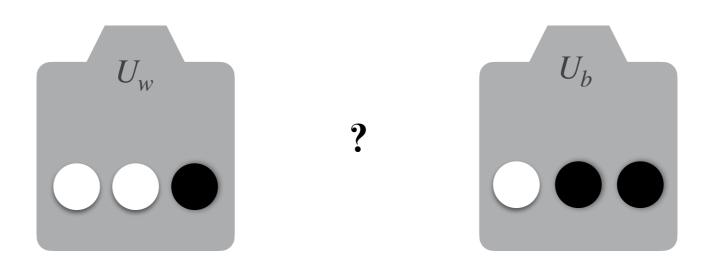


Goal: guess correctly the content of the urn, given:

your own secret observation or AND

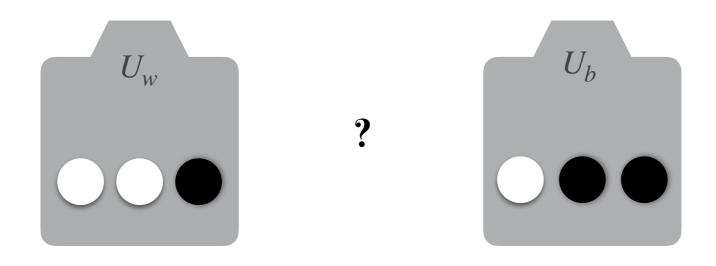
the visible guesses of previous players

First observation and guess



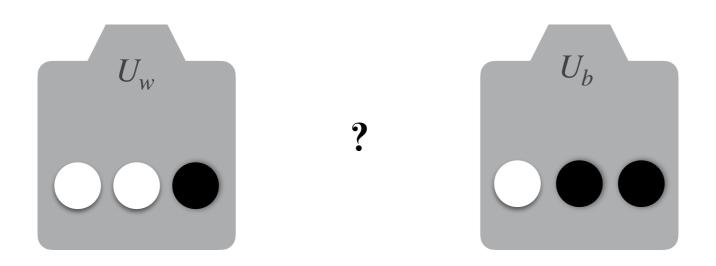
- guess U_W - if observe
- if observe

First observation and guess



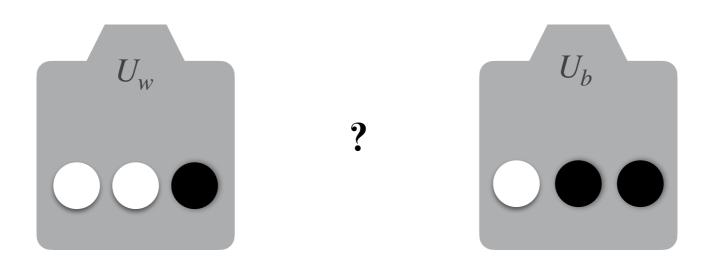
igcup guess U_W

Second observation and guess



- observe U_W + \bigcirc : guess U_W

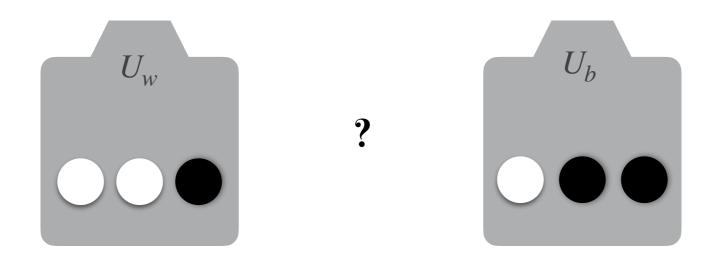
Third observation and guess



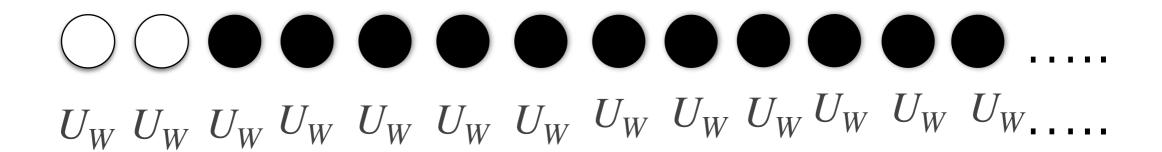
 U_W U_W \bigcirc : guess U_W

 U_W U_W : guess U_W

Conclusion: this is rational!?



Objection?



But...what if agents were really **really** smart?

Answer: Make agents maximally smart

Probabilistic DEL Model Bayesian reasoning AND (unbounded) higher-order reasoning. 3.3. Probabilistic DEL Modeling

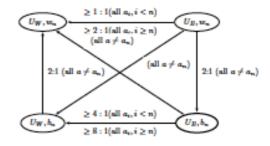
15



Note that this is just a "bird's view" representation: the actual model \mathcal{M}_{n-1} has 2^{n-2} states. To see what happens after one more observation e_n by agent n, take the update produce of this representation with the event model \mathcal{E}_n , given by:



The resulting product is:



where for easier reading we skipped the numbers representing the probabilistic information associated to the diagonal arrows (numbers which are not relevant for the proof).

By lumping again together all indistinguishable U_W -states in M_{n-1} , and similarly all the U_H -states, and reasoning by cases for agent a_n (depending on her actual observation), we obtain:

$$U_W \longrightarrow 2: 1(\text{all } a_i, i \le n)$$

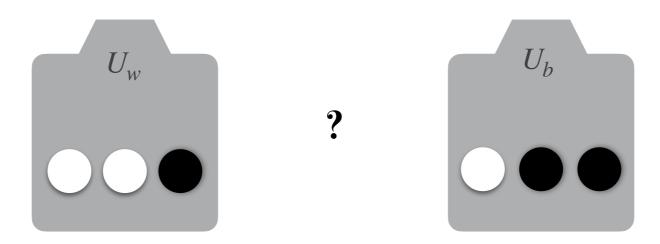
$$\ge 4: 1(\text{all } a_i, i > n)$$

$$U_B$$

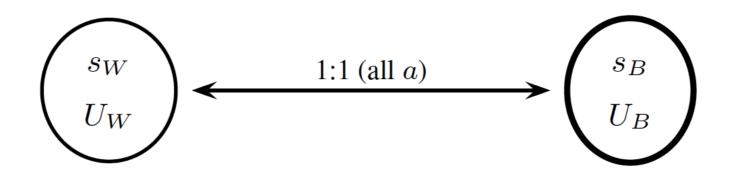
Again, this is just a bird's view: the actual model has 2^n states. But the above partial representation is enough to show that, in this model, we have $[U_W : U_B]_{a_i} \ge 2$ for all i < n + 1, and $[U_W : U_B]_{a_i} \ge 4$ for all $i \ge n + 1$.



Initial situation model



$$P(U_W) = P(U_B) = \frac{1}{2}$$



(first) marble observation: action model



$$w_1 \mid pre(U_W) = \frac{2}{3}$$

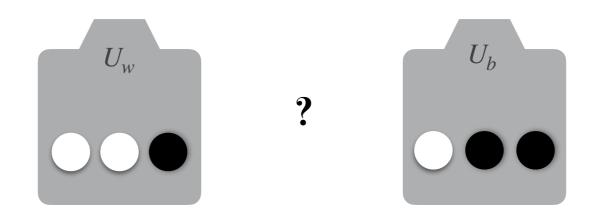
$$pre(U_B) = \frac{1}{3}$$

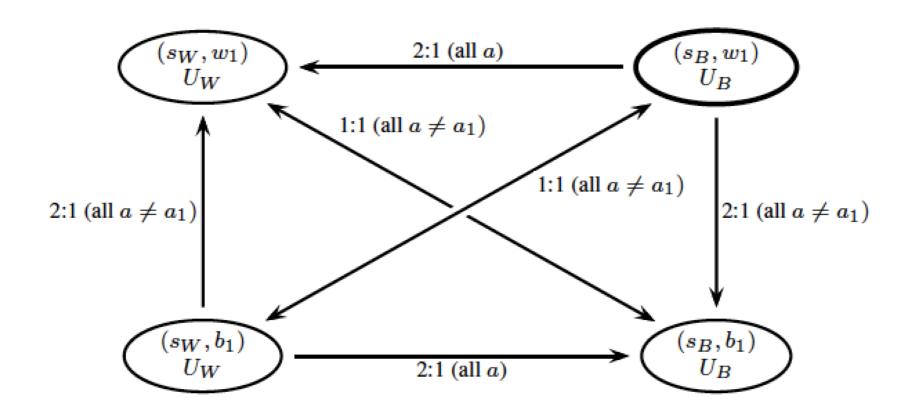
$$+ 1:1 \text{ (all } a \neq a_1)$$

$$pre(U_B) = \frac{2}{3}$$

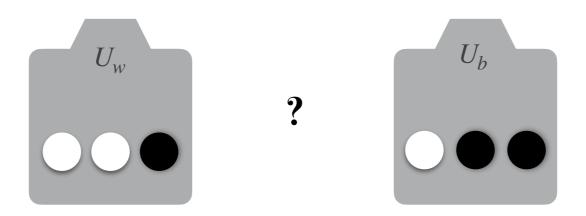
$$pre(U_B) = \frac{2}{3}$$

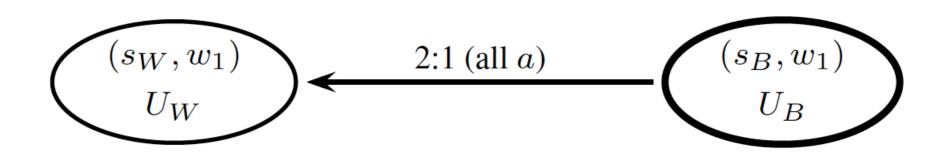
After the first observation



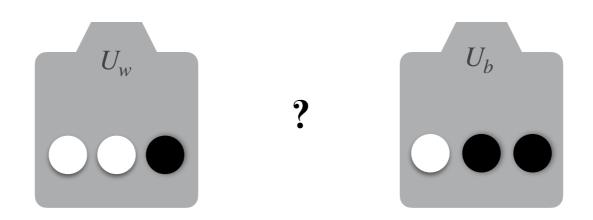


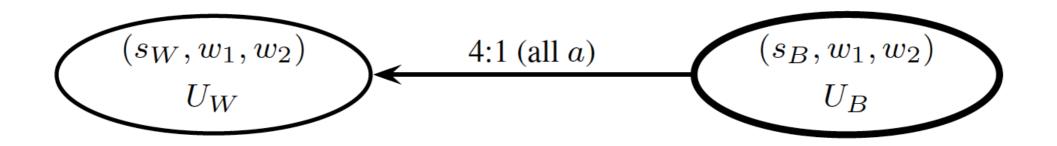
After the first agent announces her guess



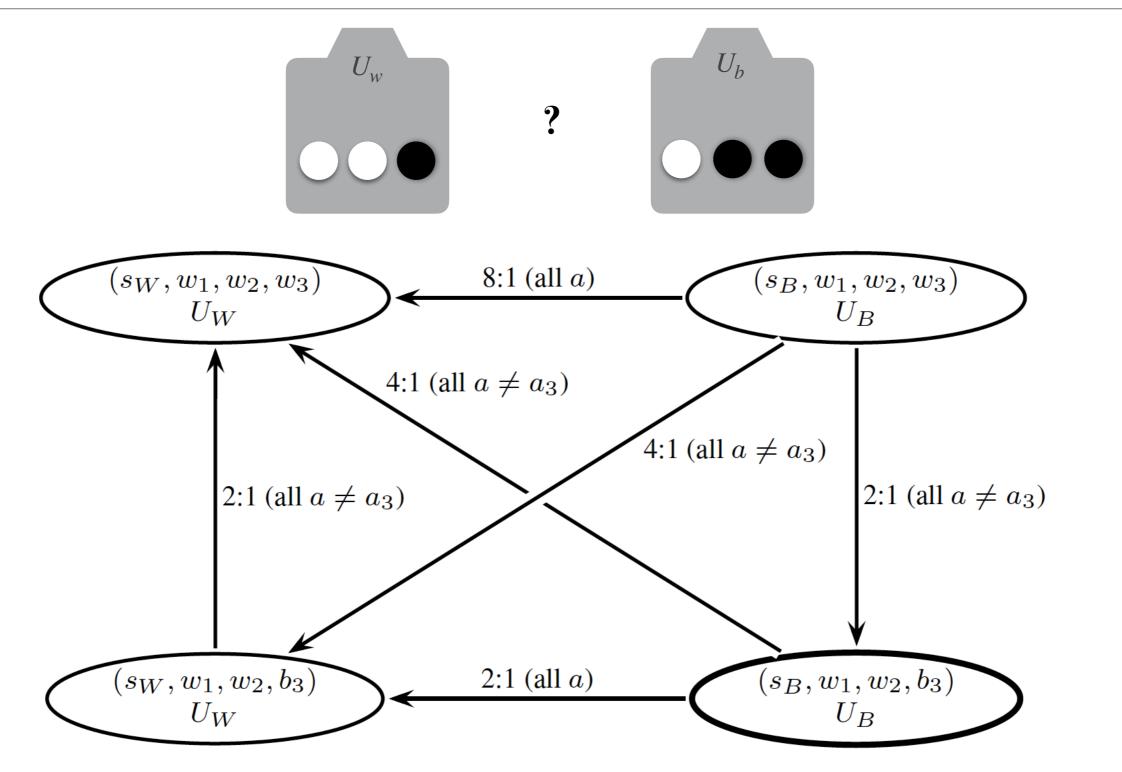


After the second agent announces her guess





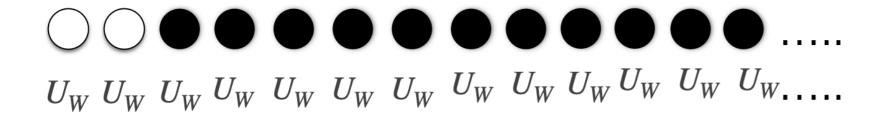
After the third observation



 $[U_W:U_B]_{a_3} > 1$ is now common knowledge

Conclusion: Still perfectly rational!

Captures the inescapability of rational cascades, even for **very** smart agents.



3.3. Probabilistic DEL Modeling

$$U_W$$

$$\geq 2 : 1(\text{all } a_i, i < n)$$

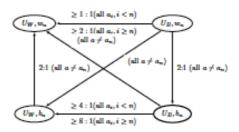
$$\geq 4 : 1(\text{all } a_i, i \geq n)$$

$$U_B$$

Note that this is just a "bird's view" representation: the actual model \mathcal{M}_{n-1} has 2^{n-2} states. To see what happens after one more observation e_n by agent n, take the update produce of this representation with the event model \mathcal{E}_n , given by:



The resulting product is:



where for easier reading we skipped the numbers representing the probabilistic information associated to the diagonal arrows (numbers which are not relevant for the proof).

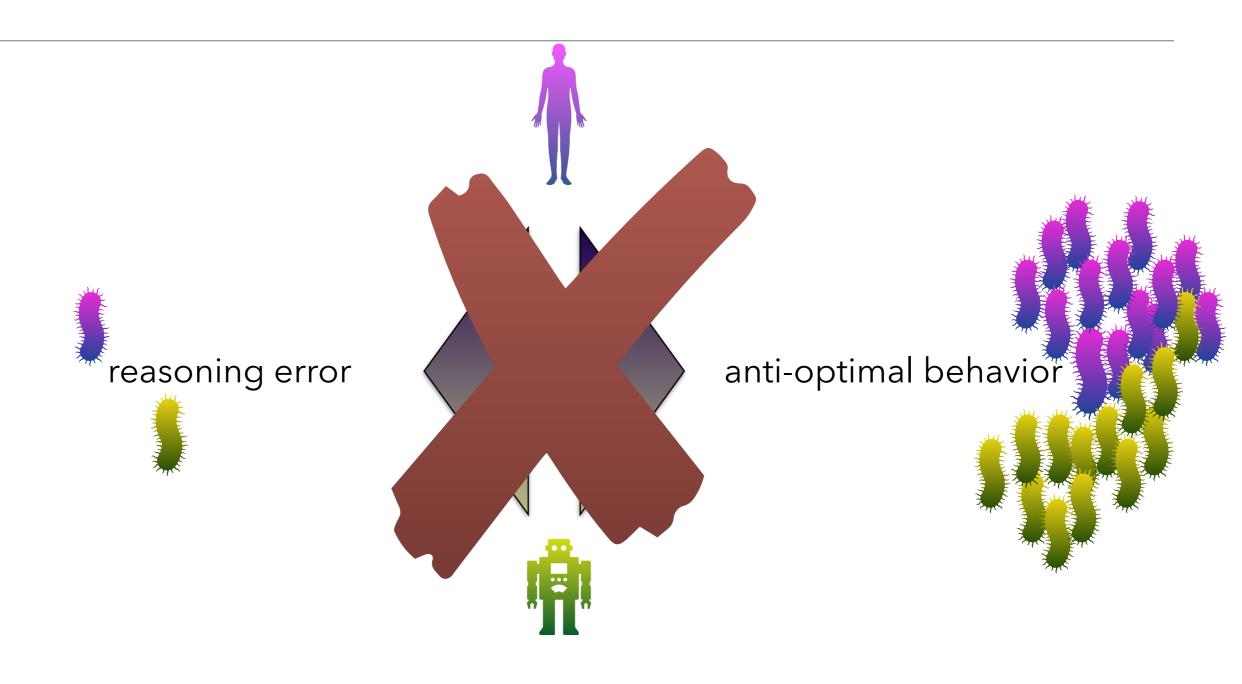
By lumping again together all indistinguishable U_W -states in \mathcal{M}_{n-1} , and similarly all the U_H -states, and reasoning by cases for agent a_n (depending on her actual observation), we obtain:

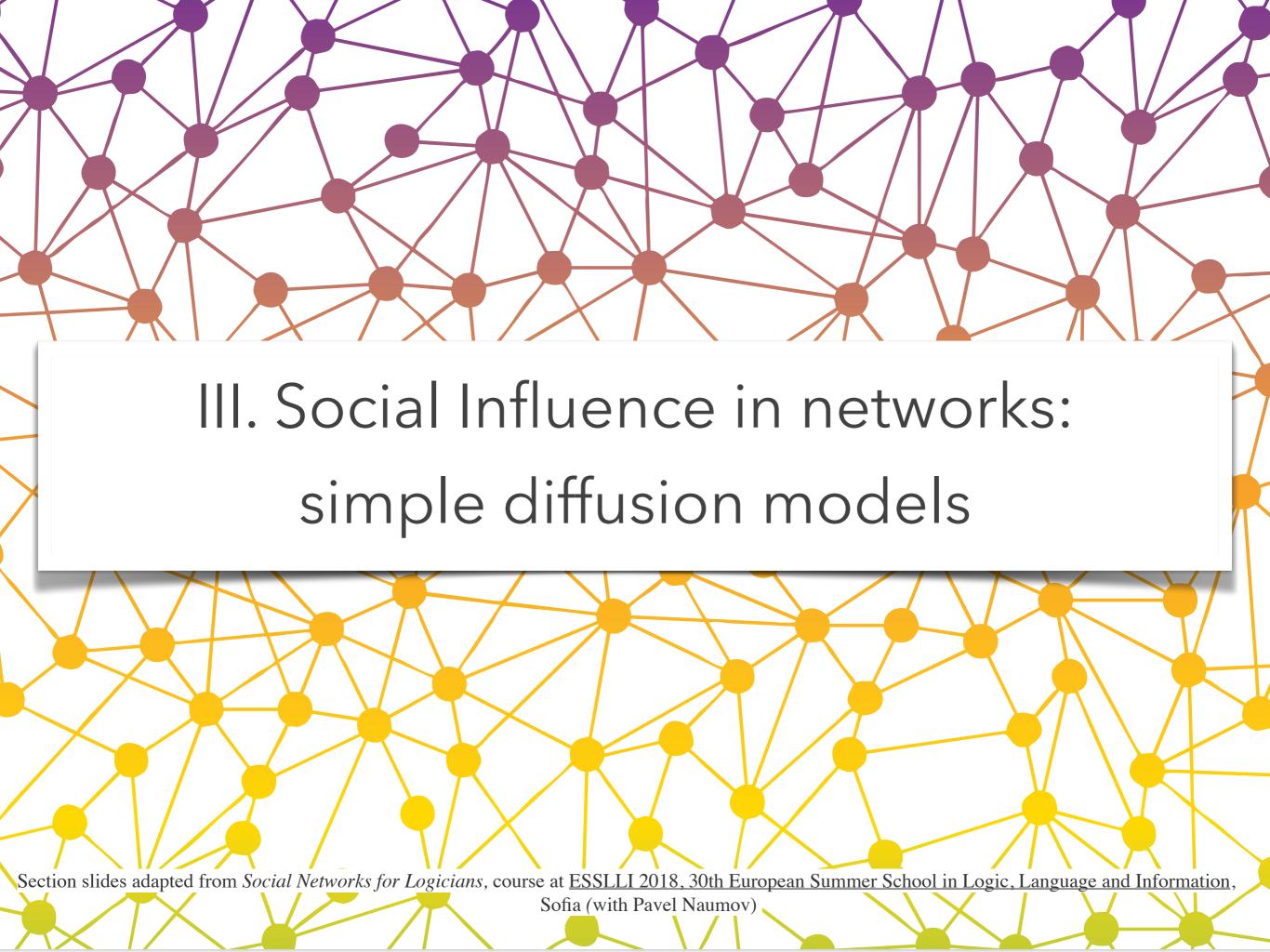
$$U_W$$
 $\geq 2 : 1(\text{all } a_i, i \leq n)$
 $\geq 4 : 1(\text{all } a_i, i > n)$

Again, this is just a bird's view: the actual model has 2^n states. But the above partial representation is enough to show that, in this model, we have $[U_W : U_B]_{a_i} \ge 2$ for all i < n + 1, and $[U_W : U_B]_{a_i} \ge 4$ for all $i \ge n + 1$.

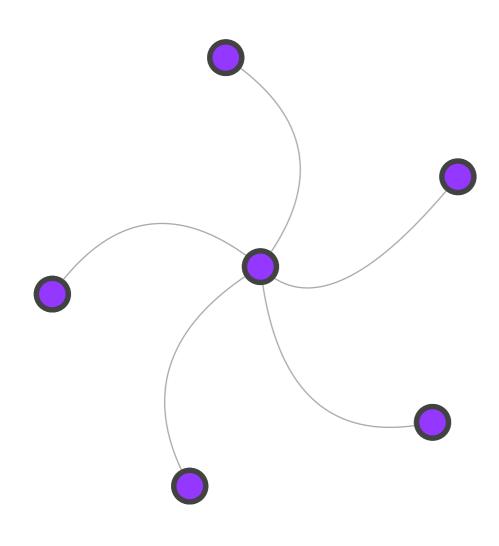
45

What does our DEL model show?





1) Threshold Models



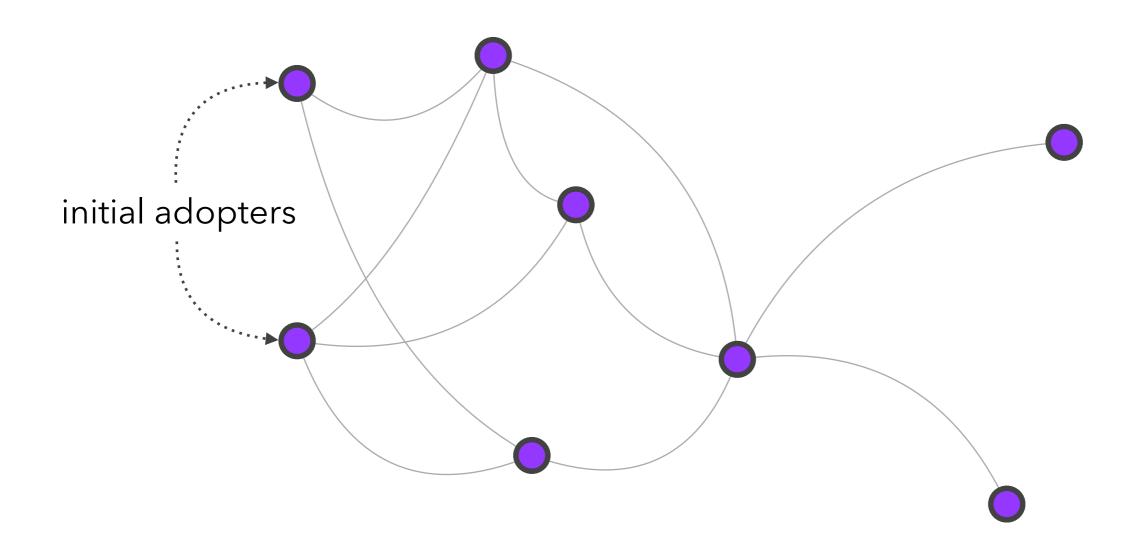
 θ is a (uniform) threshold value

Rule: agent adopts (a new color) if the ratio of her neighbors who already display it is at least θ

$$\theta = 0.5$$

"Complete cascade"

$$\theta = 0.5$$

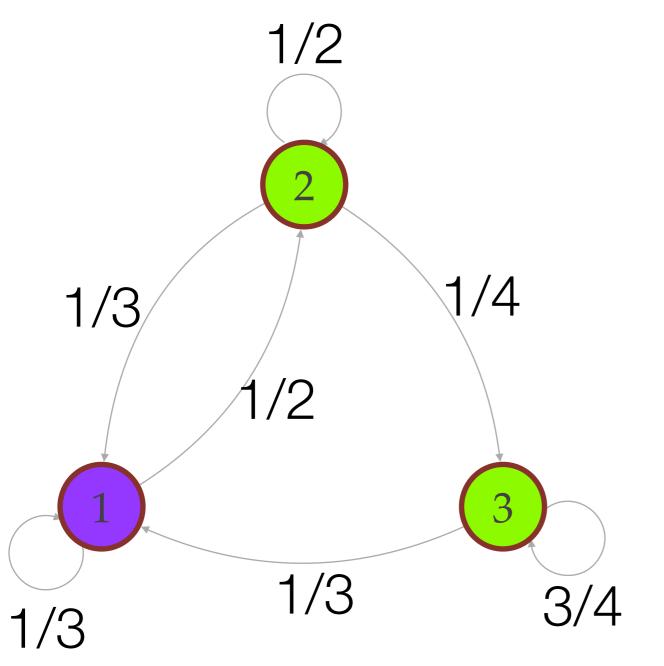


"Cluster-Cascade" Theorem

Theorem (folklore)

All nodes will eventually be infected if and only if among nodes who are not infected there is no cluster of density higher than 1- θ .

2) DeGroot Model



$$T = \begin{pmatrix} 1/3 & 1/3 & 1/3 \\ 1/2 & 1/2 & 0 \\ 0 & 1/4 & 3/4 \end{pmatrix}$$

$$\bar{p}_1 = T\bar{p}_0 \begin{pmatrix} 1/3 & 1/3 & 1/3 \\ 1/2 & 1/2 & 0 \\ 0 & 1/4 & 3/4 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1/3 \\ 1/2 \\ 0 \end{pmatrix}$$

$$\bar{p}_2 = T\bar{p}_1 \begin{pmatrix} 1/3 & 1/3 & 1/3 \\ 1/2 & 1/2 & 0 \\ 0 & 1/4 & 3/4 \end{pmatrix} \begin{pmatrix} 1/3 \\ 1/2 \\ 0 \end{pmatrix} = \begin{pmatrix} 5/18 \\ 5/12 \\ 1/8 \end{pmatrix}$$

$$\bar{p}_n = T\bar{p}_{n-1} = T^n\bar{p}_0$$

Convergence in the DeGroot Model

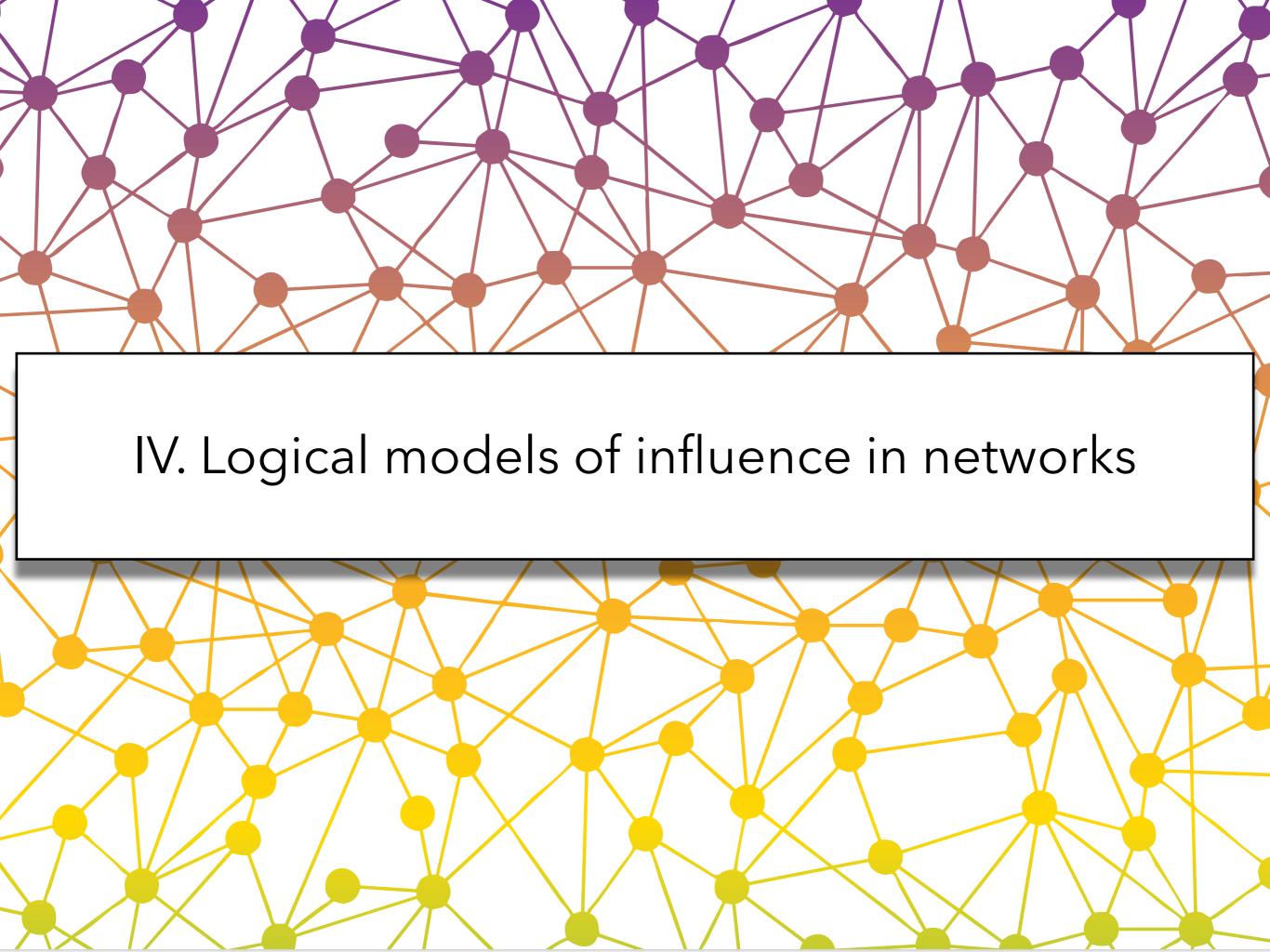
A DeGroot model converges if and only if in each strongly connected closed set, the greatest common divisor of all cycles is equal to 1.

What type of results? (again)

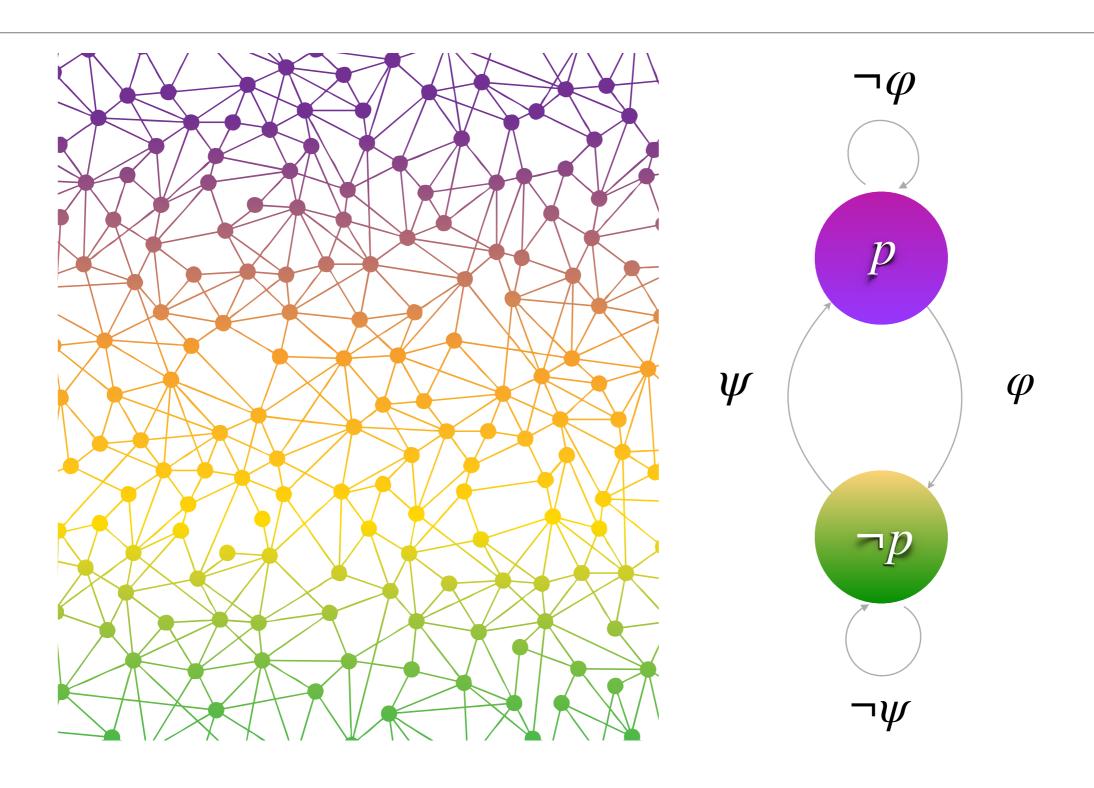
Type of results network analysis is typically interested in (given one class of networks, and one class of rules):

- which diffusion states are reachable from which?
- which diffusion processes stabilize?
- what graphs guarantee stabilization?

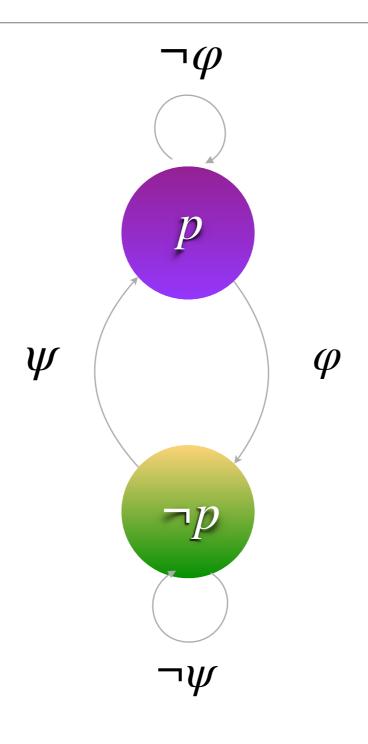
Can logic help with any of these?



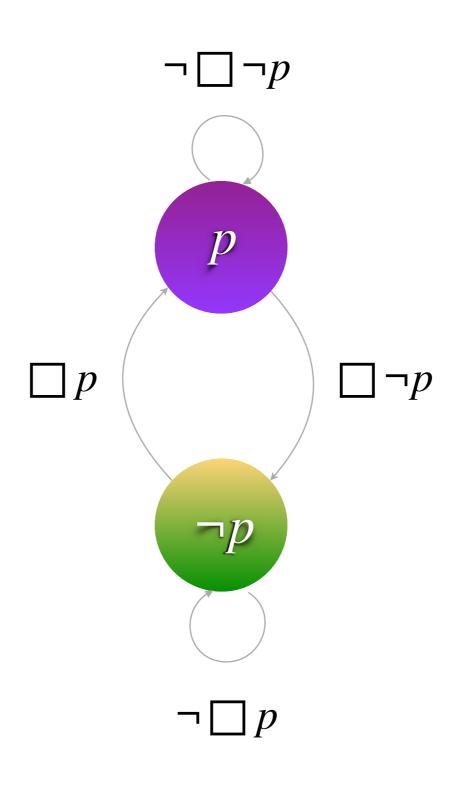
The idea



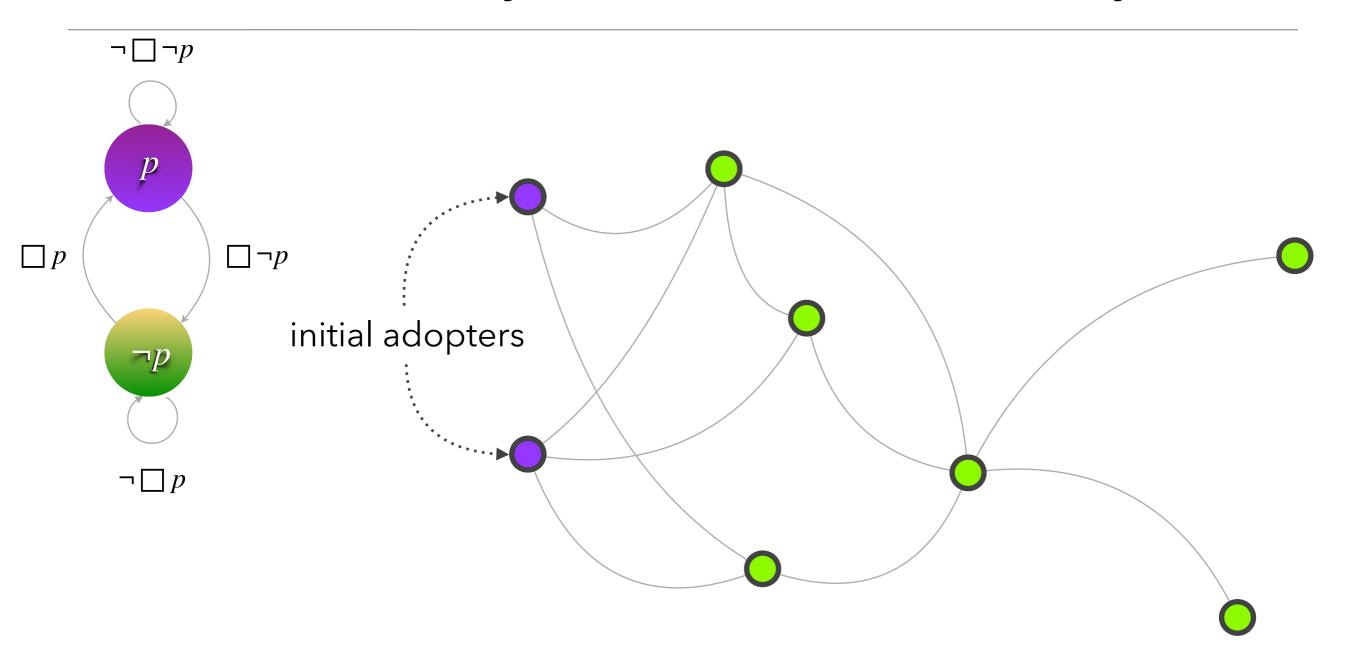
Minimal example: 2 states/colors



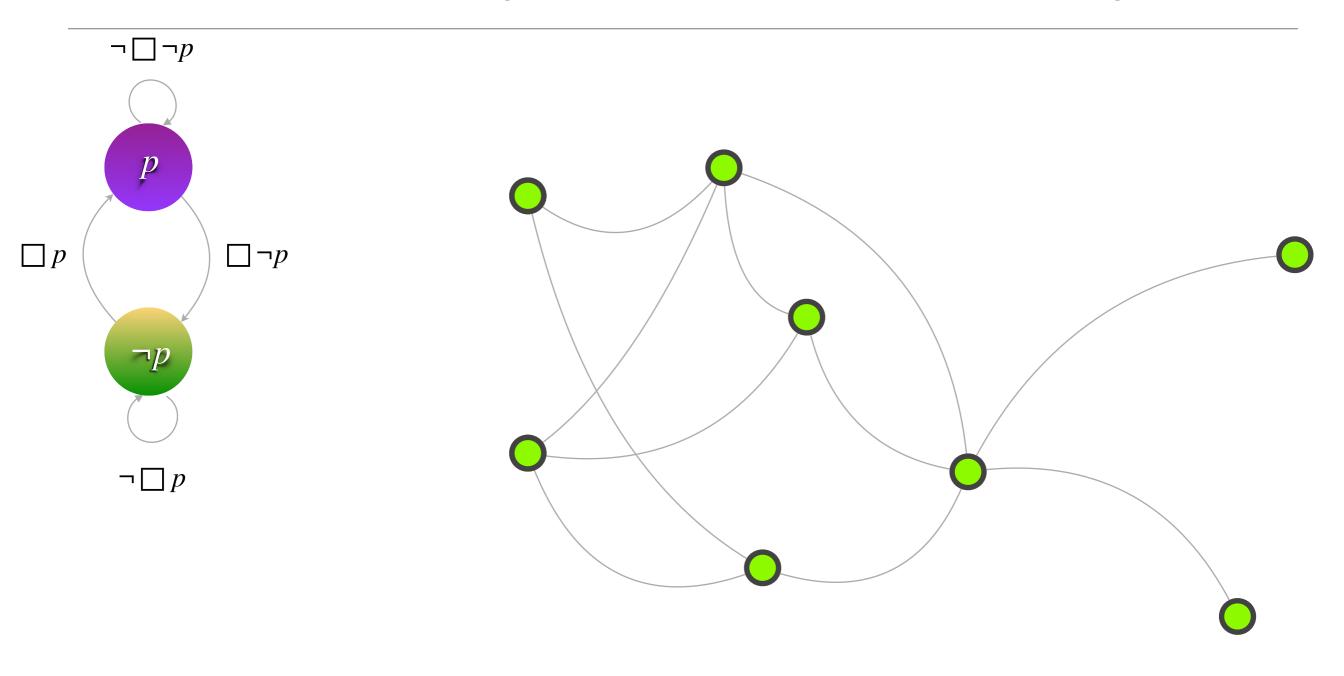
Minimal example: unanimity



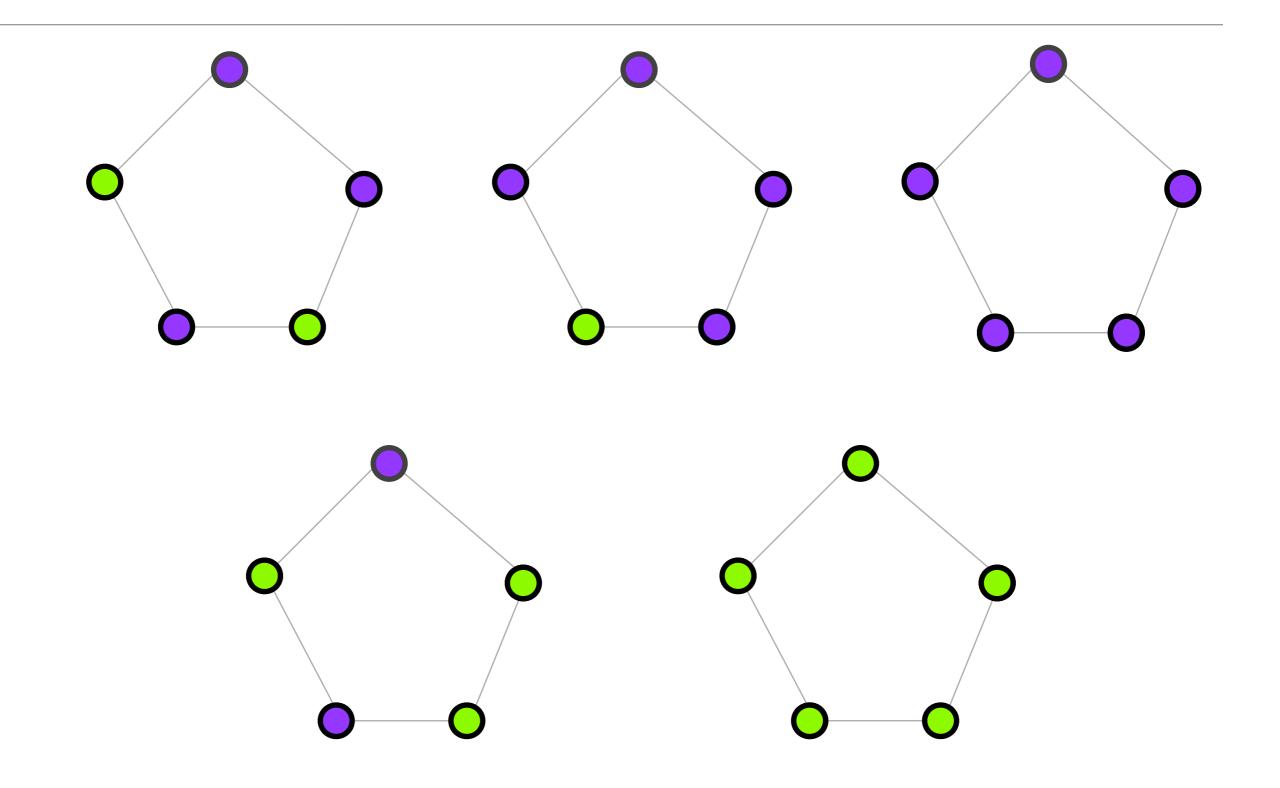
Diffusion dynamics under unanimity



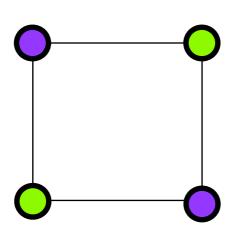
Diffusion dynamics under unanimity

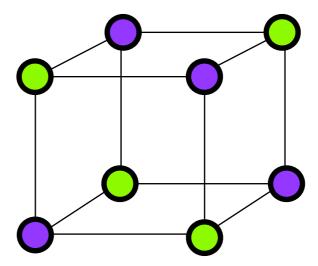


Stabilization



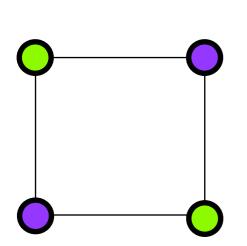
Oscillation

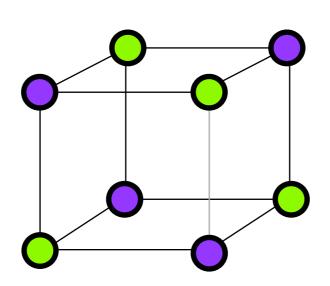


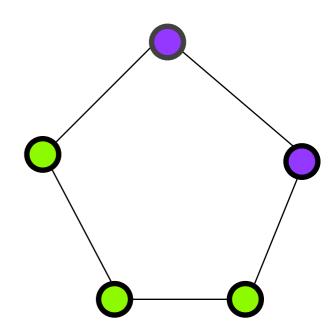


Stabilization conditions

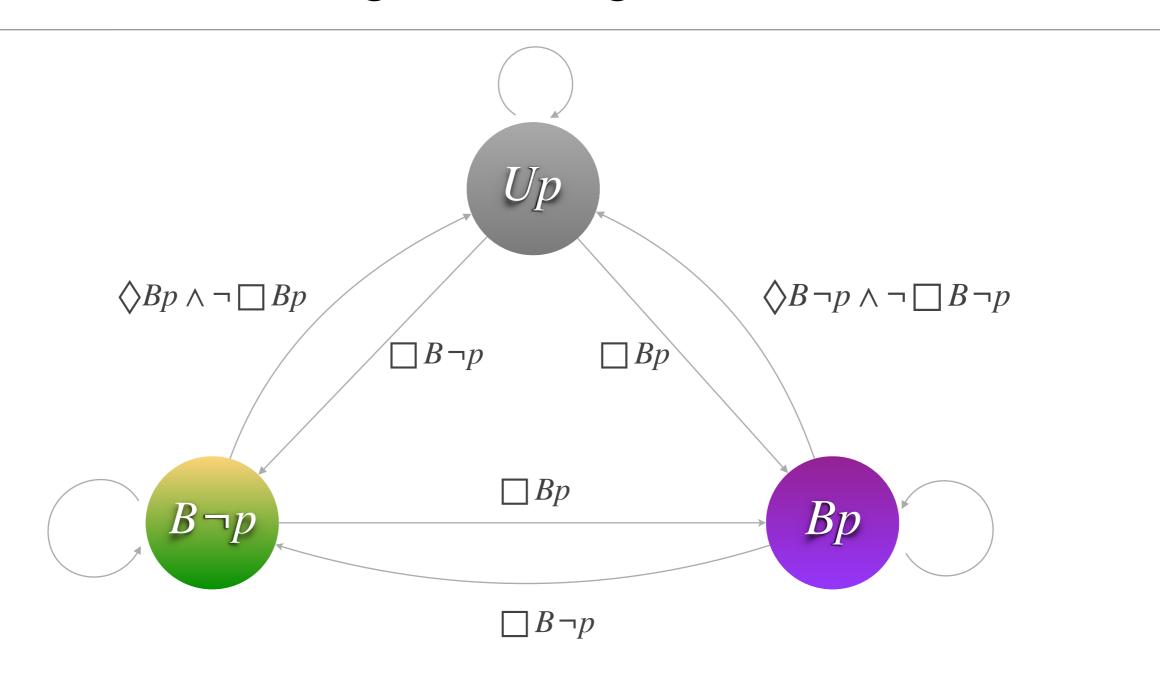
Graph has 2-coloring if and only if it has no odd-length cycles.





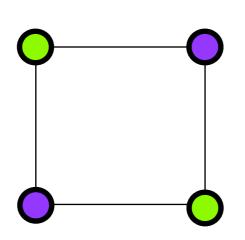


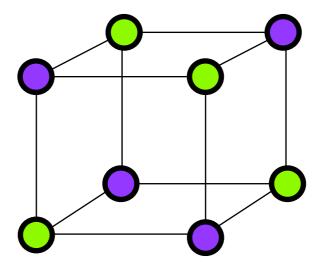
More fine-grained agents: 3 states?





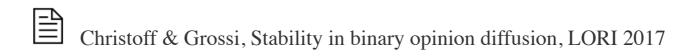
Oscillation?





More theorems about diffusion stabilization (from the perspective of judgment aggregation) in :

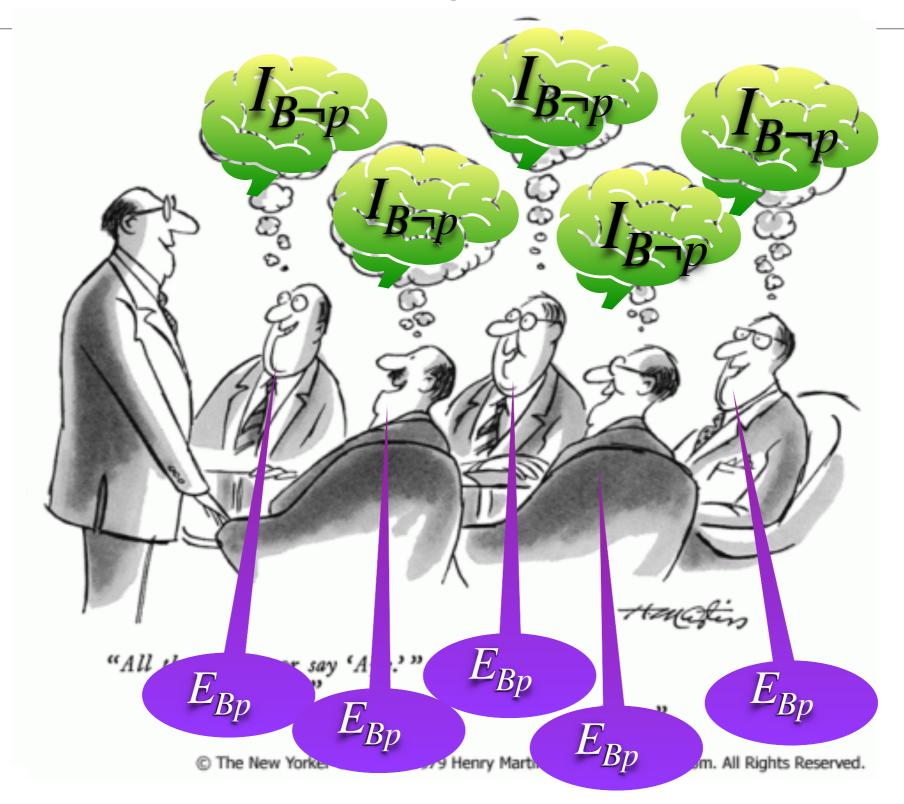
Grandi, Lorini & Perrussel, Propositional Opinion Diffusion, AAMAS15



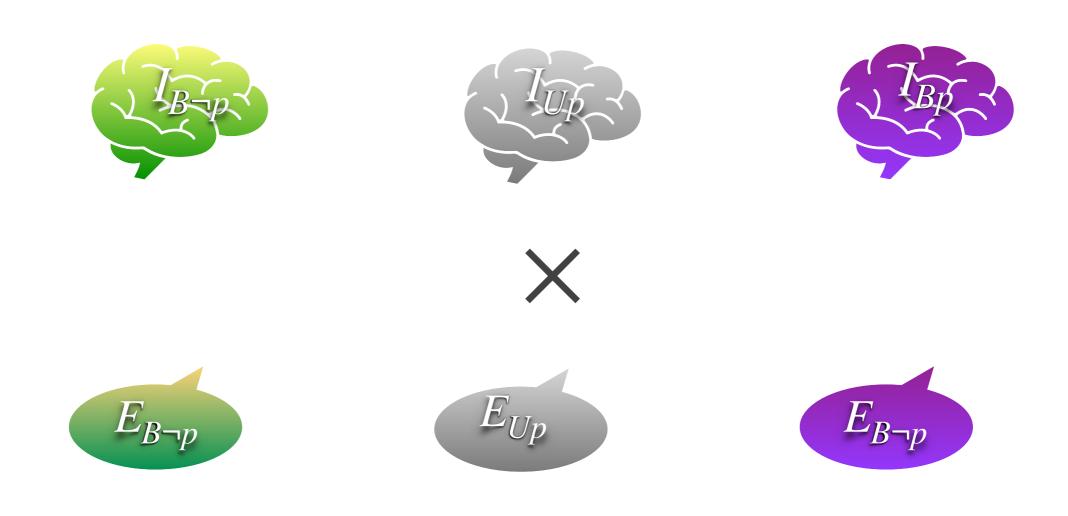
Even more fine-grained models?



Even more fine-grained models?



Even more fine-grained agents: 9 states?





Christoff & Hansen "A two-tiered formalization of social influence" (LORI 2013)



Christoff, Hansen & Proietti "Reflecting on social influence in Networks" (2016) Journal of Logic, Language & Information

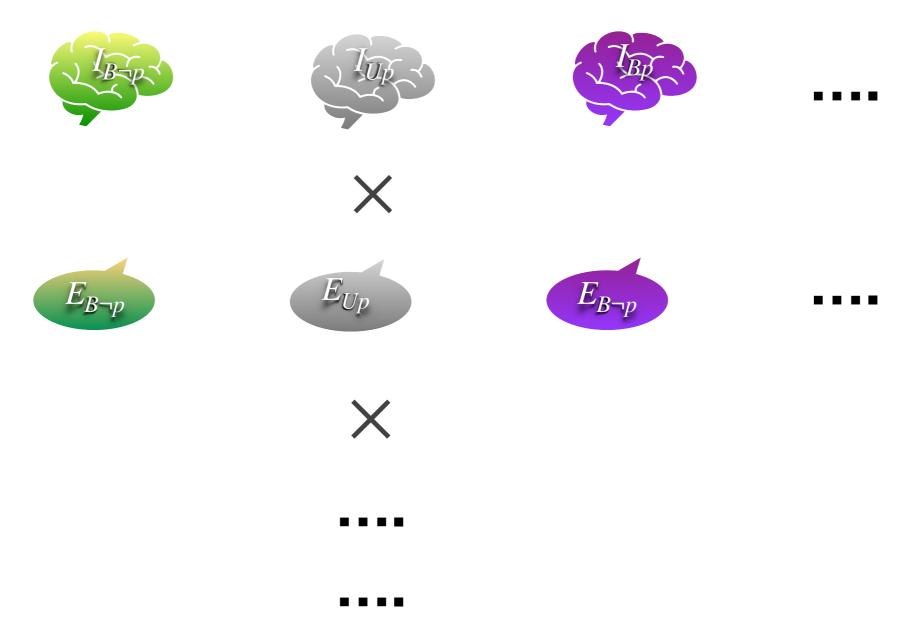
	T	/E\E	/E\E	/E\E	m 1
_	Inner state	$\langle F \rangle E_B \varphi$	$\langle F \rangle E_B \neg \varphi$	$\langle F \rangle E_U \varphi$	Type 1
1	$I_B \varphi$				$\sim E_B \varphi$
2	$I_B \neg \varphi$	1	1	1	$\sim E_B \neg \varphi$
3	$I_U arphi$				$\sim E_U \varphi$
4	$I_B arphi$				$\sim E_B \varphi$
5	$I_B \neg \varphi$	1	1	0	$\sim E_B \neg \varphi$
6	$I_U arphi$				$\leadsto E_U \varphi$
7	$I_B \varphi$				$\sim E_B \varphi$
8	$I_B \neg \varphi$	1	0	1	$\sim E_U \varphi$
9	$I_U arphi$				$\leadsto E_U \varphi$
10	$I_B \varphi$				
11	$I_B \neg \varphi$	1	0	0	$\sim E_B \varphi$
12	$I_U arphi$				
13	$I_B \varphi$				$\sim E_U \varphi$
14	$I_B \neg \varphi$	0	1	1	$\sim E_U \varphi$ $\sim E_B \neg \varphi$
15	$I_U arphi$				$\sim E_B \neg \varphi$
16	$I_B \varphi$				
17	$I_B \neg \varphi$	0	1	0	$\sim E_B \neg \varphi$
18	$I_U arphi$				
19	$I_B \varphi$				$\sim E_B \varphi$
20	$I_B \neg \varphi$	0	0	1	$\sim E_B \neg \varphi$
21	$I_U arphi$				$\sim E_U \varphi$
22	$I_B \varphi$				$\sim E_B \varphi$
23	$I_B \neg \varphi$	0	0	0	$\sim E_B \neg \varphi$
24	$I_U arphi$				$\sim E_U \varphi$

Example of result: Dissolving pluralistic ignorance in networks

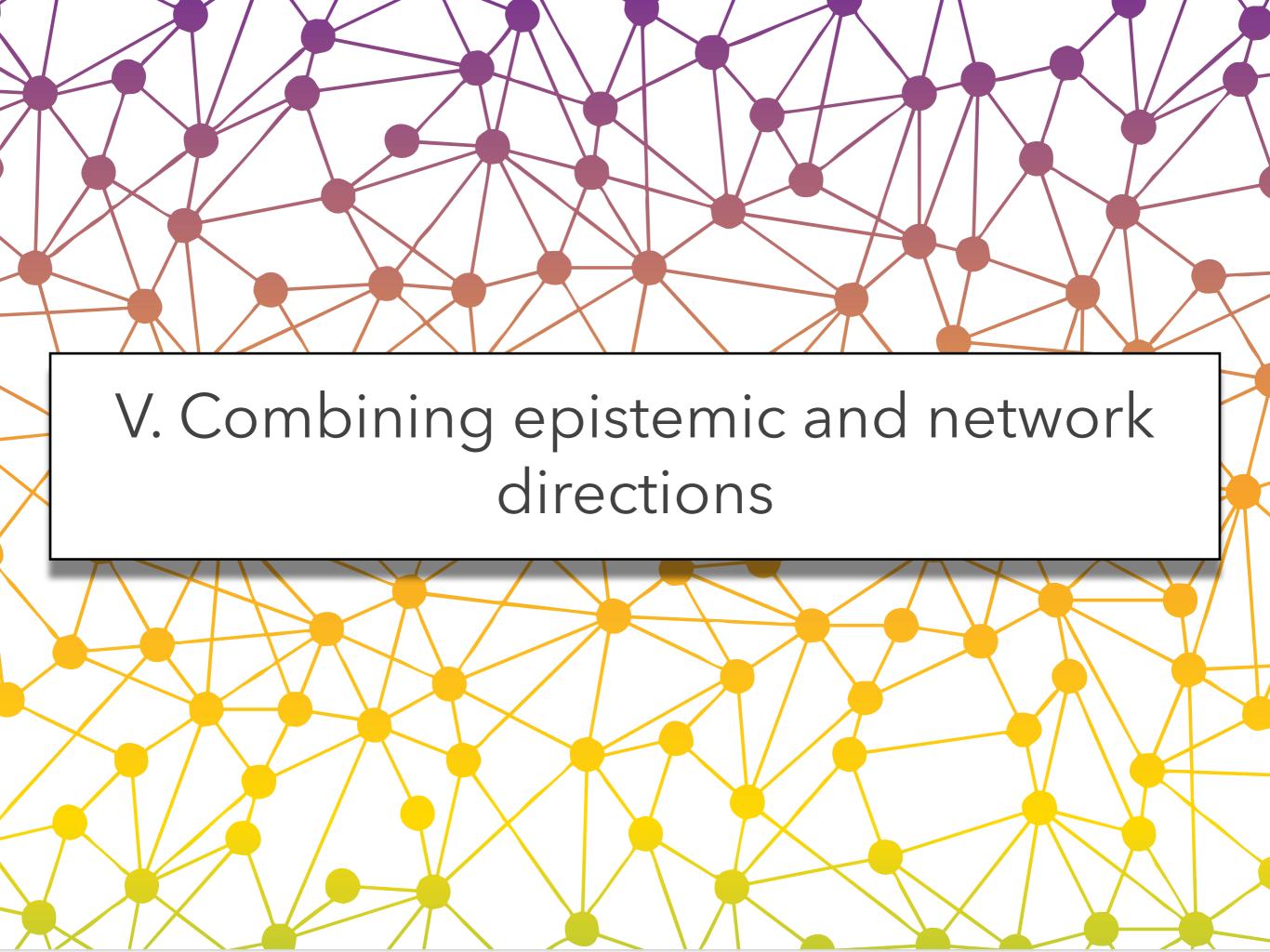
Proposition 2. Let $\mathcal{M} = (A, \sim, g, \nu)$ be a finite, connected, symmetric network model in a state of unstable pluralistic ignorance. Then the following are equivalent:

- (i) After a finite number of updates by the influence event \mathcal{I} , \mathcal{M} will end up in a stable state where pluralistic ignorance is dissolved, i.e. there is a $k \in \mathbb{N}$ such that $\mathcal{M} \otimes^{\kappa} \mathcal{I} \models G(I_B \varphi \wedge E_B \varphi)$ and $\mathcal{M} \otimes^{\kappa} \mathcal{I} = \mathcal{M} \otimes^{k+1} \mathcal{I}$.
- (ii) There is an agent that expresses her true belief in φ for two rounds in a row, i.e. there is an $a \in A$ and $a k \in \mathbb{N}$ such that $\mathcal{M} \otimes^k \mathcal{I}, a \models E_B \varphi$ and $\mathcal{M} \otimes^{k+1} \mathcal{I}, a \models E_B \varphi$.
- (iii) There are two agents that are friends and both express their true beliefs in φ in the same round, i.e. there are $a, b \in A$ and $a k \in \mathbb{N}$ such that $a \sim b$, $\mathcal{M} \otimes^k \mathcal{I}, a \models E_B \varphi$, and $\mathcal{M} \otimes^k \mathcal{I}, b \models E_B \varphi$.
- (iv) There are two agents that are friends and have paths of the same length to the agent named by i, i.e. there are agents $a, b \in A$ and $a k \in \mathbb{N}$ such that $a \sim b$, $\mathcal{M}, a \models \langle F \rangle^k i$, and $\mathcal{M}, b \models \langle F \rangle^k i$.
- (v) There is a cycle in \mathcal{M} of odd length starting at the agent named by i, i.e. there is a $k \in \mathbb{N}$ such that $\mathcal{M} \models @_i \langle F \rangle^{2k-1}i$.
- (vi) There is a cycle in \mathcal{M} of odd length, i.e. there is a $k \in \mathbb{N}$ and $a_1, a_2, ..., a_{2k-1} \in A$ such that $a_1 \sim a_2, a_2 \sim a_3, ..., a_{2k-2} \sim a_{2k-1}, a_{2k-1} \sim a_1$.

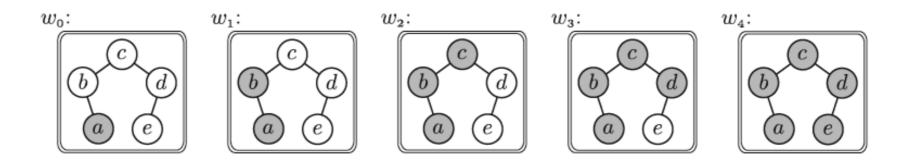
Even more fine-grained? n layers, m values







DEL of threshold diffusion



Model 3 diffusion policies:



adopt whenever enough of your neighbors have adopted

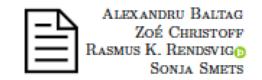


adopt whenever YOU KNOW THAT enough of your neighbors have adopted



 adopt whenever YOU KNOW THAT enough of your neighbors WILL have adopted (at some point)

Compare the 3 diffusion policies: not that big a difference!



Logic as modeling tool

I have presented 3 examples of insight from logical perspective:

- Inescapability of cascades for agents with unbounded higher-order rationality (probabilistic DEL)
- Diffusion dynamics and network structures relation (modal/hybrid/fixed point logics for social networks)
- Insight on how the behavior of "very smart" agents might not differ so much from the ones of "bacteria-like" agents (diffusion epistemic logic)

Beyond what I mentioned so far...

Rich logic toolbox by now, to capture for instance:

- what happens in diffusion in the long run directly ("ability-logics"):
 - Christoff & Naumov (2019), Social Networks Diffusion with Recalcitrant Agents, Journal of Applied Logic
 - Ågotnes & Christoff (2020), Reasoning about cascading abilities in Networks, Netreason@ECAI
- how the network structure evolves:
 - how networks with friends and enemy to tend towards balance:
 - Xiong & Ågotnes (2020), On the Logic of Balance in Social Networks, JOLLI
- Hoek, Kuijer, & Wáng (2020), Logics of Allies and Enemies: A Formal Approach to the Dynamics of Social Balance Theory, IJCAI
 - how links tend to be created/deleted based on agents similarity:
 - Smets & Velázquez-Quesada (2020), A Closeness and Priority-Based Logical Study of Social Network Creation, JOLLI

